

## Magnetic Reconnection

The dominant mechanism for dissipating magnetic energy in the universe. Converts magnetic energy into high-speed flows and energetic particles. Underlies important phenomena in the laboratory and nature

⇒ disruptions in tokamaks and other fusion experiments.

⇒ solar and stellar flares

⇒ flares from pulsar magnetospheres

⇒ magnetospheric substorms

⇒ gamma ray bursts?

⇒ driver of cosmic rays?

Required for

⇒ the dynamics

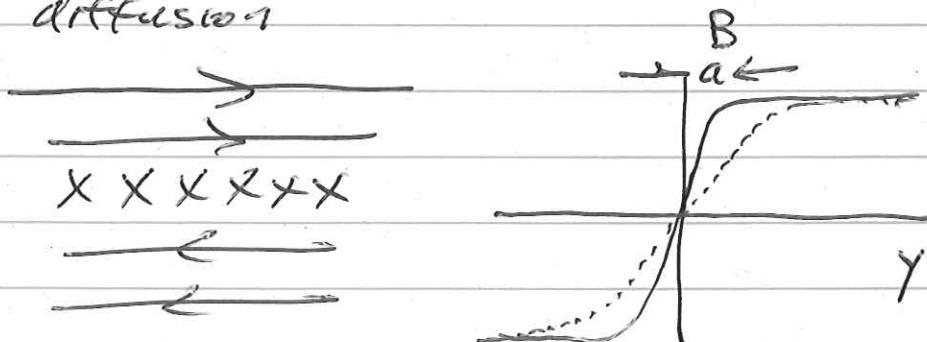
⇒ accretion around compact objects etc.

## Basic questions

- 1) What is the time scale for energy release
- 2) Why is the onset so sudden?
- 3) When does it occur?
- 4) What is the mechanism for the production of energetic particles?

⇒ flares, tokamaks, substorms,  
cosmic rays?

Magnetic energy can be released as a result of diffusion



$$\frac{\partial}{\partial t} B - \frac{3c^2 \sigma}{4\pi} \frac{\partial}{\partial y} B = 0$$

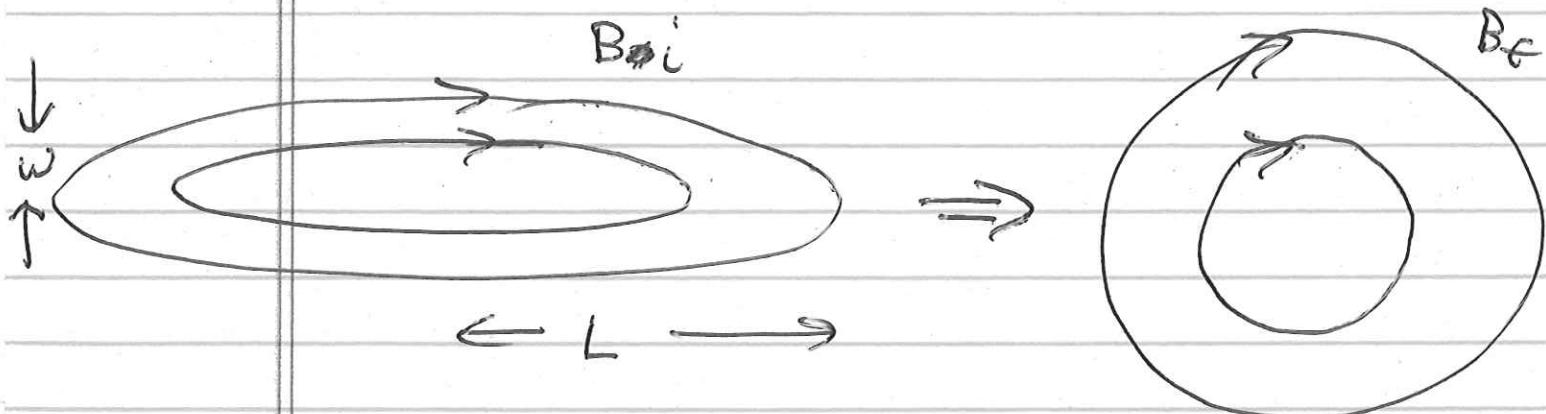
$$\tau_r \sim \frac{4\pi a^2}{3c^2} = \text{resistive time}$$

Diffusion time scales:

	<u>Resistive Time</u>	<u>Observed Release Time</u>
formaltes	1-10 s	100 usec
solar flares	$\sim 10^4$ yrs.	$\sim 2$ minutes
magnetospheric substorms	$\sim \infty$	30 minutes

### Basic Physics

Energy release from squashed bubble



Magnetic tension causes  
squashed bubble to become round

$$\mathbf{F} = -\nabla \left( P + \frac{\mathbf{B}^2}{8\pi} \right) + \frac{1}{4\pi} \mathbf{B} \cdot \nabla \mathbf{B}$$

Energy release

$\Rightarrow$  use conservation for ideal motion  
flux  $\propto$  area

$$\text{flux: } B_i w \sim B_f R$$

$$\text{area: } Lw \sim R^2$$

$$W_f = \frac{B_f^2}{8\pi} A = \frac{B_i^2 w^2}{8\pi R^2} A$$

$$= \frac{w^2}{R^2} w_i = \frac{w}{L} w_i$$

$$\ll w_i$$

$$\Rightarrow w_f \ll w_i$$

$\Rightarrow$  most magnetic energy is released.

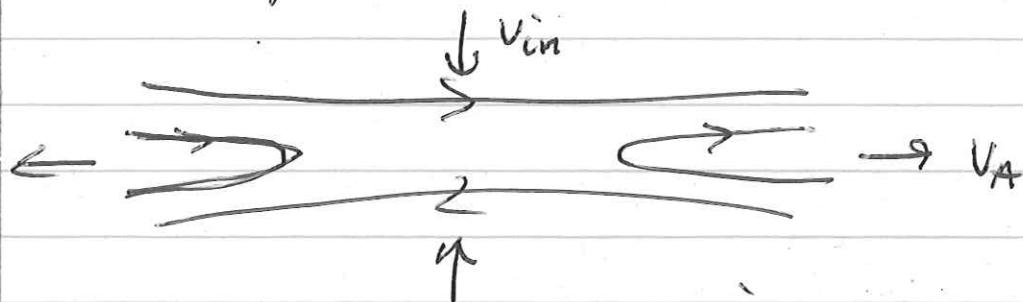
$\Rightarrow$  appears as flow energy

$$\frac{1}{2} ev^2 \sim \frac{B_i^2}{8\pi}$$

$$\Rightarrow v \sim V_A = \left( \frac{B_i^2}{4\pi e} \right)^{\frac{1}{2}}$$

$$\Rightarrow \text{characteristic time } T_A \sim \frac{L}{CA}$$

Basic phenomenon:



newly reconnected field lines release tension by expanding outward.

⇒ magnetic slingshot

Produces pressure drop around the magnetic x-line.

⇒ pressure drop pulls in plasma from above and below

⇒ new field lines break and reconnect

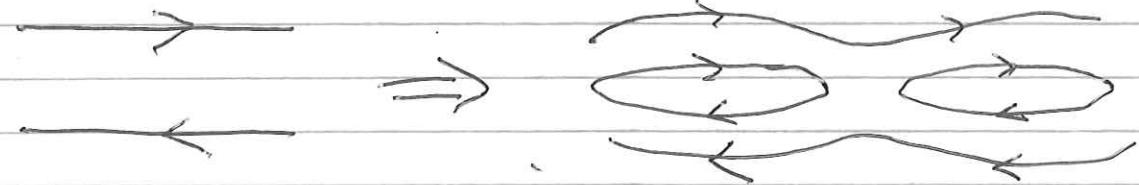
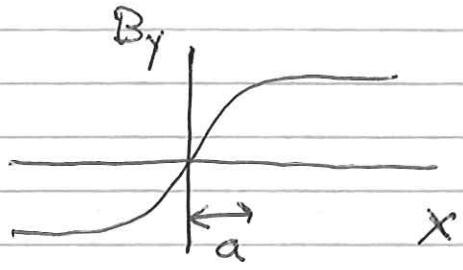
⇒ need dissipation

⇒ newly reconnected field lines expand outward

Reconnection is self-driven

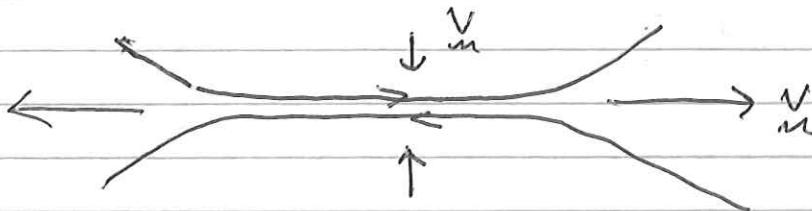
Outline

## 1) Linear theory



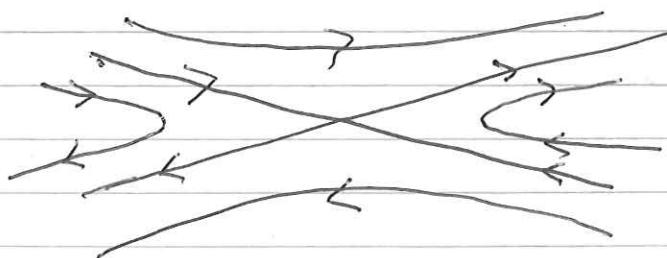
$\Rightarrow$  tearing mode

## 2) Sweet-Parker theory



macroscopic current layer

## 3) Petschek theory



open outflow

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## 2-D reduced equations

$$\rho \frac{d\mathbf{v}}{dt} = \frac{1}{c} \nabla \times \mathbf{B} - \nabla P$$

$$E_z + \frac{1}{c} v_x B_z = 3 J_z$$

$$\frac{1}{c} \frac{\partial}{\partial t} B_z + \nabla \times E_z = 0$$

$$\nabla \times B_z = \frac{4\pi}{c} J_z$$

In 2-D

$$B_z = \vec{z} \times \nabla \phi + B_{\phi} \vec{z} \Rightarrow \nabla \cdot B = 0$$

$$(\nabla \times B)_z = \left[ \nabla^2 \phi = \frac{4\pi}{c} J_z \right]$$

From Faraday's law:  $\vec{z} \times (\quad)$

$$\frac{1}{c} \frac{\partial}{\partial t} \nabla \phi + \underbrace{\vec{z} \times (\nabla \times E)}_0 = 0$$

$$\nabla E_z - \cancel{\vec{z} \times \vec{E}}$$

$$\nabla \left( -\frac{1}{c} \frac{\partial}{\partial t} \phi + E_z \right) = 0$$

$$E_z = \frac{1}{c} \frac{\partial}{\partial t} \phi$$

## Ohm's Law

$$\vec{J}_0 \cdot (\frac{1}{\rho} \nabla \phi + \mathbf{V} \times (\frac{1}{\mu_0} \times \vec{\mathbf{B}}) \frac{1}{\rho} = \vec{G})$$

$$E_z + V \cdot \nabla \phi \frac{1}{\rho} = G$$

$$\boxed{\frac{\partial \phi}{\partial t} + \mathbf{V} \cdot \nabla \phi = \frac{3c^2}{4\pi} \gamma^2 \psi}$$

convective  
Diffusion  
Eqn. for  
flux  $\psi$ .

If  $\frac{2}{\delta t} \ll \frac{1}{\gamma_{ms}}$   $\Rightarrow$  nearly incompressible

Take curl of momentum equation

$$\nabla \cdot \mathbf{V} \approx 0$$

$$\Rightarrow \mathbf{V} = \vec{\omega} \times \nabla \phi \quad \text{of stream.}$$

$$\nabla \times \mathbf{V} = \frac{1}{2} \nabla^2 \phi \quad \text{function of vorticity}$$

$$\rho_0 \vec{\omega} \cdot \nabla \times \frac{d}{dt} \mathbf{V} = - \rho_0 \vec{\omega} \cdot \left( \vec{\omega} \times \frac{d}{dt} \mathbf{V} \right)$$

$$= + \rho_0 \vec{\omega} \cdot \frac{d}{dt} \nabla \phi$$

$$= \rho_0 \left( \frac{2}{\delta t} \vec{\omega}^2 \phi + \underbrace{\vec{\omega} \cdot (\vec{\omega} \times \vec{\omega} \cdot \nabla) \nabla \phi}_{\delta_i (\vec{\omega} \times \vec{\omega} \cdot \nabla) \delta_i} \right)$$

$$\delta_i = \delta_i' \phi$$

$$\underbrace{\delta_i (\vec{\omega} \times \vec{\omega} \cdot \nabla) \delta_i}_{\frac{1}{2} \vec{\omega} \times \vec{\omega} \cdot \nabla \delta_i \delta_i}$$

$$+ \vec{\omega} \times \vec{\omega} \cdot \nabla \delta_i \delta_i$$

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$$\epsilon_0 \frac{d}{dt} \nabla^2 Q = \frac{1}{c} \vec{J} \cdot \nabla \times (\vec{J} \times \vec{B})$$

$$= \frac{1}{c} (\vec{B} \cdot \nabla \vec{J}_z - \vec{J} \cdot \nabla \vec{B}_z)$$

Since  $\nabla \cdot \vec{B} = \nabla \cdot \vec{J} = 0$

$$\vec{J} \cdot \nabla \vec{B}_z = \frac{c}{4\pi} \nabla \vec{B}_z \times \vec{J} \cdot \nabla \vec{B}_z = 0$$

$$4\pi\epsilon_0 \frac{d}{dt} \nabla^2 Q = \vec{B} \cdot \nabla \nabla^2 \psi$$

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## Relation between $\phi$ and $E_{\perp}$ ( $x, y$ direction)

$$V = - \vec{z} \times \nabla \phi$$

$$\vec{E}_{\perp} + \frac{1}{c} \vec{v} \times \vec{B}_{\perp} = 0$$

$$\vec{E}_{\perp} + \frac{1}{c} (\vec{z} \times \nabla \phi) \times \vec{B}_{\perp} = 0$$

$$\vec{z} \times \vec{E}_{\perp} + \frac{B_2}{c} \vec{z} \times \nabla \phi = 0$$

$$\vec{E}_{\perp} = - \frac{B_2}{c} \nabla \phi$$

$$E_{\parallel} = \frac{B_2 E_2 - \frac{B_2}{c} B \cdot \nabla \phi}{\epsilon}$$

$$= \frac{B_2}{B} \left( \frac{1}{c} \frac{\partial \phi}{\partial t} - \frac{1}{c} B \cdot \nabla \phi \right)$$

$$= \frac{B_2}{c B} \left( \frac{\partial \phi}{\partial t} - B \cdot \nabla \phi \right)$$

$\phi \rightarrow$  electrostatic potential

$$\frac{\partial \phi}{\partial t} + v \cdot \nabla \phi = \frac{3c^2}{4\pi} \gamma^2 \omega$$

$$\frac{B_2}{B_2} E_{\parallel} = \frac{3c^2}{4\pi} \frac{\partial \phi}{\partial t} \cancel{\times} J_2$$

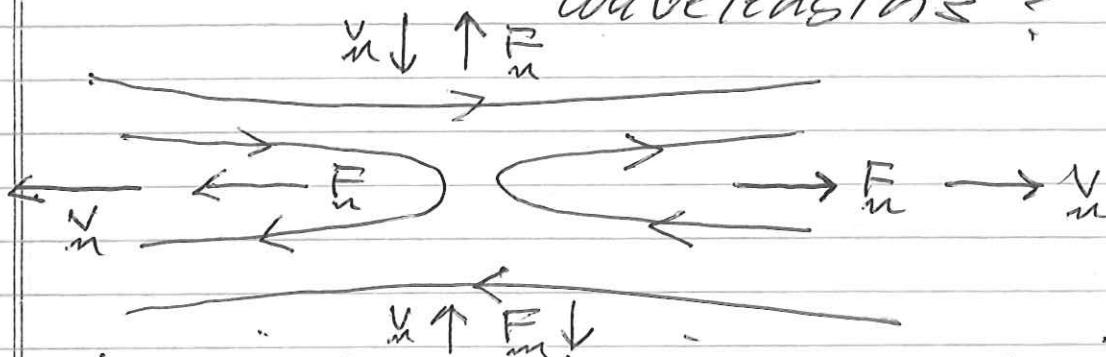
$$\boxed{E_{\parallel} \frac{B}{B_2} = J_2} \Rightarrow \text{Ohm's law}$$

## Magnetic energy

when do we expect reconnection to release magnetic energy?

→ range of unstable

wavelengths?



tension force drives reconnection :

$$F_m = B_m \cdot \nabla B_m$$

Reconnection driven where  $F_m \cdot V_m > 0$

⇒ inflow magnetically unfavorable

⇒ outflow magnetically favorable

⇒ calculate energy released

⇒ displace plasma and magnetic field to evaluate energy change

⇒ displacement increases from

$$0 \rightarrow \xi$$

$$dW_B = - \int d\chi_m d\xi_m \cdot F_m(\xi_m)$$

⇒ integrate  $\xi_m$  from 0 to  $\xi$   $\Rightarrow F_m \sim \xi_m$

$$\Delta W_B = - \frac{1}{2} \int d\chi_m \xi_m \cdot F_m(\xi_m)$$

$$\vec{B} = \hat{z} \times \nabla \psi + \frac{\hat{z}}{c} B_z$$

$$\vec{J} = \frac{1}{2} \frac{c}{4\pi} \nabla^2 \psi$$

$$\vec{F} = \frac{1}{c} \vec{J} \times \vec{B}$$

$$\Delta w_B = -\frac{1}{2} \int dx \underbrace{\vec{J} \cdot \frac{1}{c} \vec{J} \times \vec{B}}$$

$$= -\frac{1}{2} \int dx \underbrace{\vec{J} \cdot \frac{1}{c} \frac{1}{4\pi} \hat{z} \times (\hat{z} \times \nabla \psi)}_{-\nabla \psi} \nabla^2 \psi$$

$$= \frac{1}{8\pi} \int dx \underbrace{(\nabla \psi \cdot \nabla^2 \psi)}$$

$$= \frac{1}{8\pi} \int dx \underbrace{(\nabla \psi_0 \cdot \nabla^2 \tilde{\psi} + \nabla \tilde{\psi} \cdot \nabla^2 \psi_0)}$$

$$\frac{\partial \psi}{\partial t} + \nabla \cdot \nabla \psi = 0$$

$$B_{y0}'$$

$$\frac{\partial \tilde{\psi}}{\partial t} + \nabla \cdot \nabla \psi_0 = 0 \Rightarrow \tilde{\psi} = -\underbrace{\nabla \cdot \nabla \psi_0}_{= -\nabla_x \psi_0'}$$

$$B_y^0 = \frac{\partial}{\partial x} \psi_0$$

$$= -\nabla_x \psi_0'$$

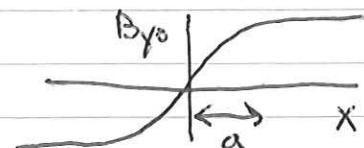
$$= \frac{1}{8\pi} \int dx \underbrace{(-\tilde{\psi} \nabla^2 \tilde{\psi} + B_{y0}' \nabla \cdot \nabla \tilde{\psi})}$$

$$= \frac{1}{8\pi} \int dx \left( |\nabla \tilde{\psi}|^2 - B_{y0}'' \nabla_x \tilde{\psi} \right)$$

second order  
magnetic perturbation

$$\tilde{\psi}^{(2)} = -\underbrace{\nabla \cdot \nabla \tilde{\psi}}$$

$$= \frac{1}{8\pi} \int dx \left( |\nabla \tilde{\psi}|^2 + \frac{B_{y0}''}{B_{y0}} \tilde{\psi}^2 \right)$$



$$\Delta w_B = \frac{1}{8\pi} \int dx \left( |\nabla \tilde{\psi}|^2 + \underbrace{\frac{B_{y0}''}{B_{y0}} \tilde{\psi}^2}_{\sim k^2} \right)$$

$$\Rightarrow k^2 a^2 < 1 \text{ for } \frac{\Delta w_B < 0}{\sim k^2} \sim \frac{1}{a^2}$$

Linearized Equations  
(slab,  $\partial/\partial z = 0$ )

$$\nabla_{\perp}^2 \tilde{\psi} = \frac{4\pi}{c} \tilde{J}_z$$

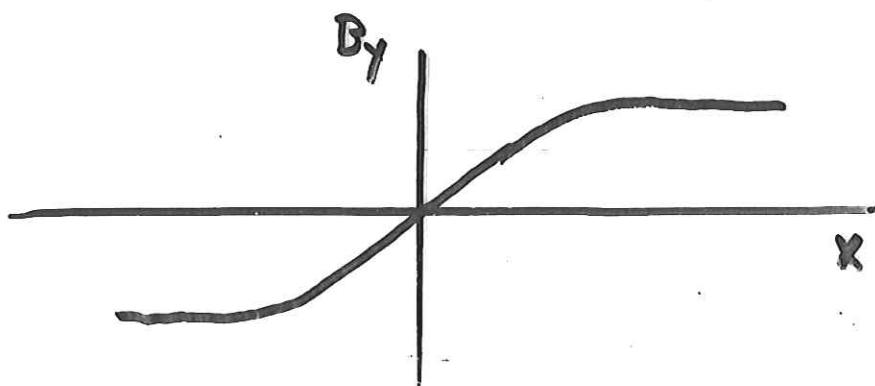
$$\gamma \rho \nabla_{\perp}^2 \tilde{\psi} = i \tilde{k}_{\parallel} \cdot \tilde{B} \frac{1}{c} \tilde{J}_z - i k_y \tilde{\psi} \frac{1}{c} \tilde{J}_z'$$

$\tilde{B}_x \tilde{J}_z'$

$$\gamma \tilde{\psi} - i \tilde{k}_{\parallel} \cdot \tilde{B} \tilde{\psi} = c \gamma \tilde{J}_z$$

$\gamma$  = growth rate

$$\tilde{k}_{\parallel} \cdot \tilde{B} = k_y B_y(x) \Rightarrow 0 \text{ at } x=0$$



## Role of Resistivity

- Ohm's Law

$$\tilde{E}_{||} = \gamma \tilde{\psi} - i k_y B_y(x) \tilde{\phi} = c_3 \tilde{J}_z$$

- to have reconnection require

$$\tilde{B}_x = -i k_y \tilde{\psi} \neq 0 \text{ at } x \approx 0$$

$$\Rightarrow \gamma \tilde{\psi} = c_3 \tilde{J}_z \text{ at } x \approx 0$$

$\Rightarrow$  resistivity required for reconnection

$\Rightarrow$  small resistivity  $\Rightarrow$  small growth rate

- away from  $x \approx 0$  where  $B_y \neq 0$  can neglect resistivity

$$\tilde{E}_{||} = \gamma \tilde{\psi} - i k_y B_y(x) \tilde{\phi} \approx 0$$

$\Rightarrow$  region around  $x \approx 0$  is a boundary layer of scale size  $\Delta \ll a$

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Ideal Region ( $\tilde{E}_{\parallel} = 0$ )  
 $(x > \Delta)$

- resistivity not important and inertia not important

$$\tilde{E}_{\parallel} = 0 \quad \text{Ohm's Law}$$

$$\tilde{\mathbf{J}}_+ = \frac{\tilde{\nabla}}{\partial_y} \mathbf{J}'_+ \quad \text{Vorticity Eqn}$$

- $\tilde{E}_{\parallel} = 0$  can be rewritten as

$$\frac{\partial \tilde{\psi}}{\partial t} + \tilde{v}_x \frac{\partial \tilde{\psi}}{\partial x} = 0$$

$\Rightarrow$  magnetic flux is frozen into the fluid

- expression for  $\tilde{\mathbf{J}}_+$  can be rewritten as

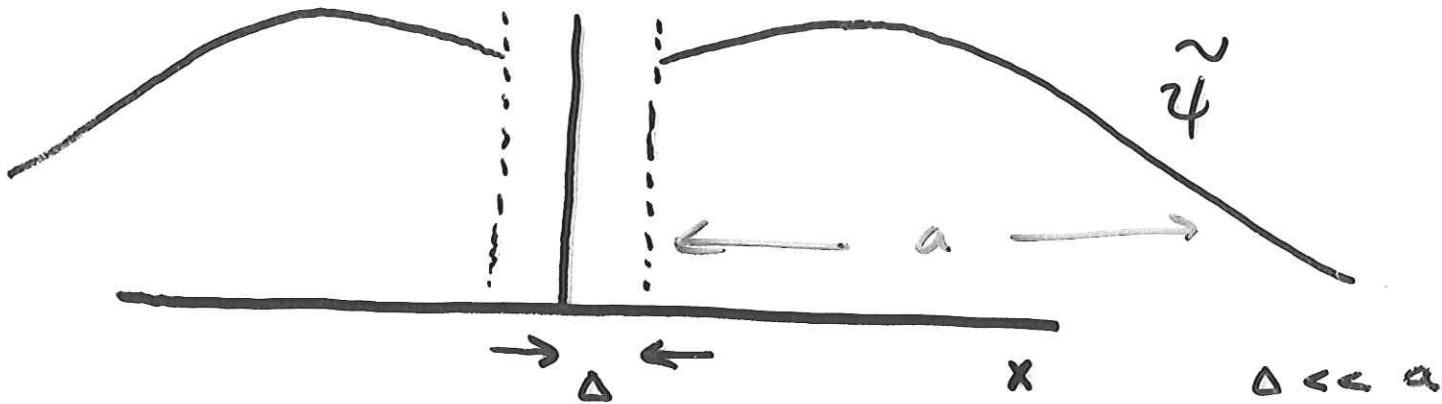
$$\tilde{\mathbf{J}}_+ = -\mathbf{g}_x \frac{\partial \mathbf{J}_+}{\partial x}$$

$\Rightarrow$  current perturbation arises from displacement of equilibrium current

- Equation for  $\tilde{\psi}$

(stab)

$$\nabla_x^2 \tilde{\psi} - \frac{B_y''}{B_y} \tilde{\psi} = 0$$



- solve equation for  $\tilde{\psi}$  subject to  $\tilde{\psi}(\infty) = 0$
- solution not valid around  $x = 0$
- characterize solution by jump in slope across  $x = 0$ .

$$\Delta' \equiv \frac{1}{\tilde{\psi}(0)} \left. \frac{\partial \tilde{\psi}}{\partial x} \right|_{-\Delta}^{+\Delta}$$

- can show

$$\Delta' = -8\pi \delta w_0 / \int dx |\tilde{\psi}|^2$$

$\Rightarrow \Delta' > 0$  for instability

- for Harris equilibrium (slab)

$$\Delta' a = 2(1 - k_y^2 a^2) / |k_y| a$$

$$B_y = B_0 \tanh\left(\frac{x}{a}\right)$$

$\Rightarrow$  note  $\Delta' > 0$  for  $k_y a < 1$

$\Rightarrow$  consistent with previous scaling argument

## Resistive Region ( $\tilde{E}_h \neq 0$ ) ( $x \sim a \ll a$ )

- $J_z'$  can be neglected
- $\nabla_{\perp}^2 \approx \frac{\partial^2}{\partial x^2}$
- $k_y \tilde{B} \approx k_y B_y' x \Rightarrow$  since  $|x| \ll a$

$$\Delta^2 \tilde{\psi}'' = \left( \frac{4\pi \gamma \Delta^2}{3c^2} \right) \left( \tilde{\psi} - \frac{x}{\Delta} \tilde{\varphi} \right)$$

$$\Delta^2 \tilde{\varphi}'' = -\frac{x}{\Delta} \left( \tilde{\psi} - \frac{x}{\Delta} \tilde{\varphi} \right)$$

$$\frac{\Delta}{a} = \left( \frac{\gamma \tau_{AY}}{k_y^2 a^2} \frac{1}{S} \right)^{1/4}$$

$$\tau_{AY} = \frac{a}{C_{AY}} \quad C_{AY}^2 = \frac{B_y'^2 a^2}{4\pi \rho}$$

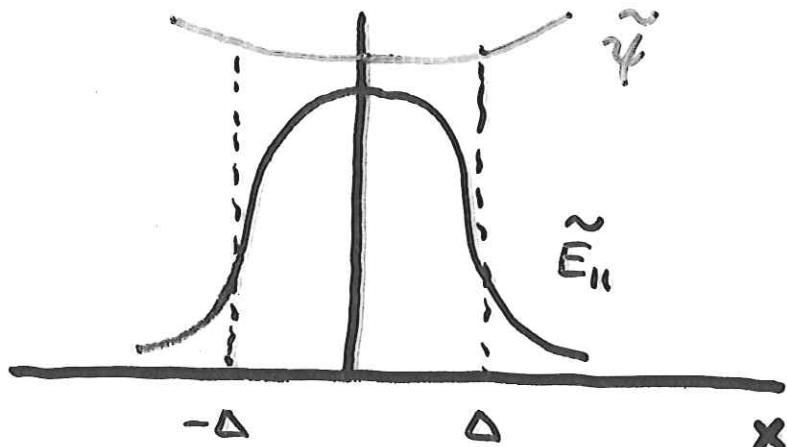
$$\tau_r = \frac{4\pi a^2}{3c^2} \quad S = \frac{\tau_r}{\tau_{AY}}$$

$\Rightarrow$   $\Delta$  is the scale length of the resistive region

$$\Delta/a \ll 1$$

- Layer equations have exact solutions

$$\tilde{E}_{\parallel} \sim \tilde{\psi} - \frac{x}{\Delta} \tilde{\varphi}$$



$$\tilde{E}_{\parallel} \rightarrow 0 \text{ for } |x| > \Delta$$

$$|x| > \Delta$$



matches  
MHD solution

- For  $\gamma \ll 3c^2/4\pi\sigma^2$ ,  $\tilde{\psi}$  is nearly constant across region  $\Delta$  so

$$\tilde{\psi}(x) \approx \tilde{\psi}(0)$$

$\Rightarrow$  constant  $\psi$  approximation

- Integrate  $\tilde{\psi}$  eqn across layer to calculate  $\Delta'$  from resistive region

$$\Delta' \approx \frac{4\pi\gamma}{3c^2} \Delta$$

## Dispersion Relation for TM

- Equate  $\Delta'$  from resistive region to that from ideal region

$$\gamma_{T_{A_y}} = S^{-3/5} \left[ \frac{\Delta' \Gamma(\frac{1}{4})}{2\pi \Gamma(\frac{3}{4})} \right]^{4/5} (k_y a)^{2/5} \ll 1$$

$$\gamma \sim S^{-3/5}$$

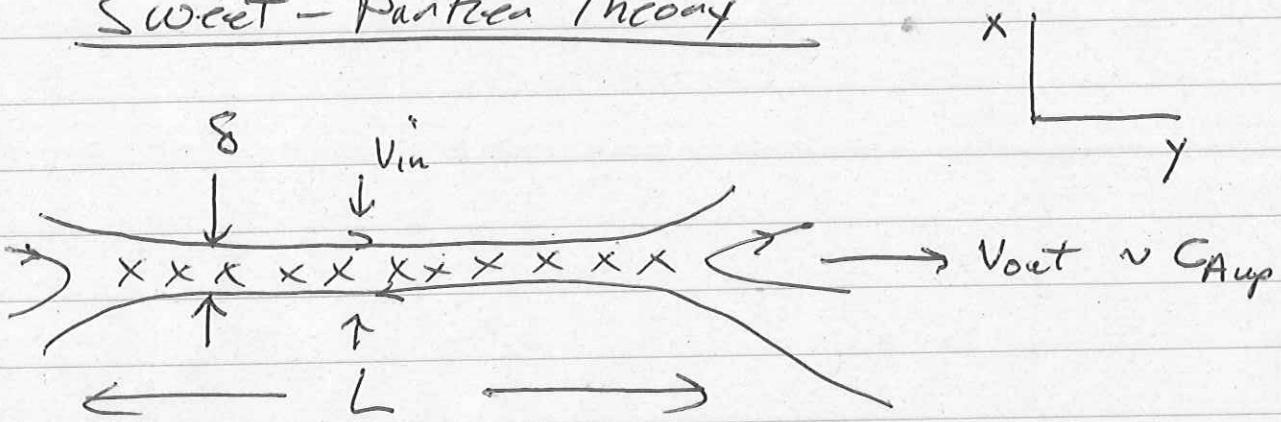
$$\Rightarrow \frac{\Delta}{a} \sim S^{-2/5} \ll 1$$

$\Rightarrow$  linear tearing mode theory tells little about reconnection or island evolution

$\Rightarrow$  theory breaks down when island width  $w$  is of order of the tearing layer width  $\Delta$ .

$\Rightarrow$  very small  $w$  !!

## Sweet-Parker Theory



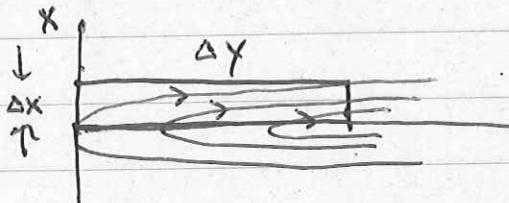
In the S-P mode plasma flows into a ~~macroscopic~~ current layer of macroscopic scale length  $L$  and a microscopic width  $\delta$  which depends on the plasma resistivity

### outflow velocity

Easiest to work directly from momentum equation along outflow direction. In steady state

$$\epsilon_0 v_y \frac{\partial}{\partial y} v_y = \frac{1}{c} J_x B_x = \frac{1}{4\pi} B_x \frac{\partial}{\partial x} B_y$$

$$\frac{\partial}{\partial y} \epsilon_0 \frac{v_y^2}{2} = \frac{1}{4\pi} B_x \frac{B_y}{\Delta x} \sim \frac{B_y^2}{4\pi \Delta y} \sim \frac{1}{6\pi} \frac{\partial}{\partial y} B_y^2$$



$$B_x \Delta y \sim B_y \Delta x$$

$$\epsilon_0 v_y^2 \sim \int dy \frac{1}{4\pi} \frac{\partial}{\partial y} B_y^2$$

$$\sim \frac{1}{4\pi} B_y^2$$

$$\boxed{v_x \sim C_{A\mu p}}$$

$\Rightarrow$  By is the magnetic field just upstream of the current layer

$\Rightarrow$  consistent with earlier squashed bubble model.

### Structure of current layer

Use the flux diffusion equation to look at the structure of the current layer <sup>along</sup> ~~and~~ the inflow direction

$$\frac{\partial}{\partial t} \frac{\partial \Phi}{\partial t} + v_x \frac{\partial}{\partial x} \Phi = \frac{\eta c^2}{4\pi} \frac{\partial^2}{\partial x^2} \Phi$$

In steady state flux is convected into the current layer at a ~~constant~~ constant rate.

$E_{rec} = \frac{1}{c} \frac{\partial \Phi}{\partial t}$  is the reconnection electric field

$\Rightarrow$  rate of flux reconnection

Resistivity again only important in a narrow region of scale length  $\delta$ . Just upstream of  $\delta$ , flux is simply convected by flow

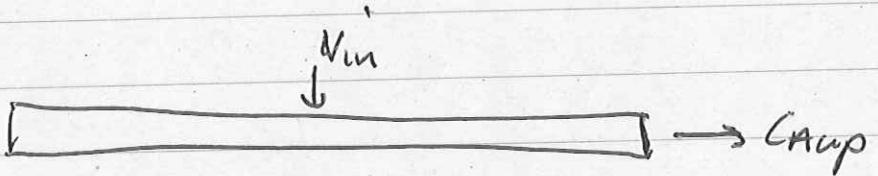
$$\frac{\partial \Phi}{\partial t} \sim v_x \frac{\partial \Phi}{\partial x} \sim v_{\infty} \frac{\Delta \Phi}{\delta} \sim$$

Within the current layer ( $J_x \sim \frac{\delta^2}{\delta x^2} 4 / \text{ampc}$ )  
 flux diffuses due to resistivity

$$\frac{\delta \Phi}{\delta t} \sim \frac{3C_L^2}{4\pi} \frac{\Delta \Phi}{\delta^2}$$

$$\Rightarrow \cancel{V_{in}} \quad V_{in} \cancel{\frac{\Delta \Phi}{\delta^2}} \sim \frac{3C_L^2}{4\pi} \frac{\Delta \Phi}{\delta^2}$$

$$\boxed{V_{in} \sim \frac{3C_L^2}{4\pi} \frac{1}{\delta}}$$



On the downstream edge of the current layer

$$\frac{\delta \Phi}{\delta t} \sim V_y \frac{\partial}{\partial y} 4 \sim C_{Aux} \frac{\Delta \Phi}{L}$$

$$\sim V_{in} \frac{\Delta \Phi}{\delta}$$

$$\Rightarrow \boxed{C_{Aux} \delta \sim L V_{in}}$$

$\Rightarrow$  continuity of flow  
 since nearly incompressible

$$C_{Aux} \delta \sim L \frac{3C_L^2}{4\pi} \frac{1}{\delta}$$

Q5b

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$$\frac{1}{\tau_A} \equiv \frac{C_{Amp}}{L}, \quad \frac{3c^2}{4\pi} \frac{1}{L^2} = \frac{1}{\tau_r}$$

$$\left(\frac{\delta}{L}\right)^2 = \left(\frac{\tau_A}{\tau_r}\right)^{\frac{1}{2}} \ll 1$$

$$V_{in} = \frac{C_{Amp}}{L} \delta \sim C_{Amp} \left(\frac{\tau_A}{\tau_r}\right)^{\frac{1}{2}} \ll C_{Amp}$$

$\Rightarrow$  too slow to explain observations  
 $T \sim 100 \text{ eV}$

$\Rightarrow$  e.g. solar flares  $L \sim 10^4 \text{ km}$   
 $B \sim 200 \text{ G}$ ,  $n \sim 10^9 / \text{cm}^3$

$$S = \frac{\tau_n}{\tau_A} \approx 10^{12} = \text{Lundquist number.}$$

$$\tau_A \sim 10 \text{ sec}$$

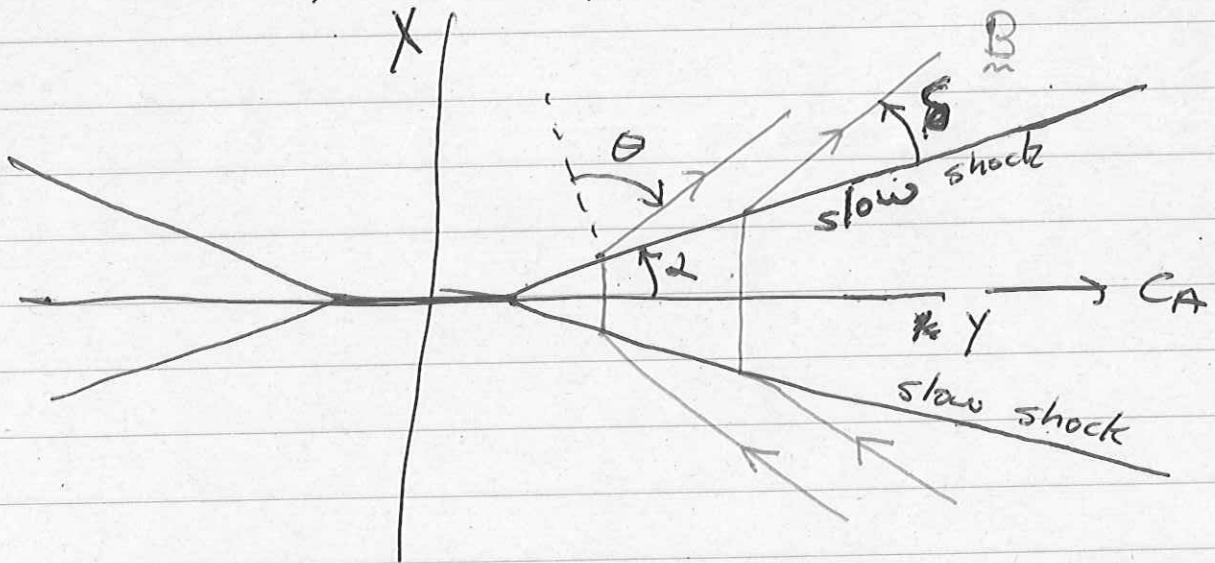
$$\tau_{sp} \sim 10(10^6) \text{ sec} \sim 10^7 \text{ s}$$

observed times  $\sim 100 \text{ sec}$

## Petchete Theory

S-P model is slow because of the length of the current sheet. Can shorten current sheet to microscopic scale and thereby increase reconnection rate?

Petchete proposed that the dissipation region (where  $\beta$  important) was short and that slow shocks bound the outflow region, which opens as a fan



The slow shocks are stationary ~~downstream~~ and divert the plasma inflow into the outflow direction. Down stream of the SS.  $v_x = 0$  and  $B_y = 0$ . ~~the flow conditions are~~ ~~dictated~~ ~~from the hydrodynamics~~

$\Rightarrow$  typically  $\lambda_s$  small and  $\theta \sim \frac{\pi}{2}$

The reduced eqns are incompressible

$\Rightarrow$  don't properly describe the slow shock

$\Rightarrow$  return to full MHD equations

Key assumptions:

~~switch off shock~~

$$\beta_{t2} = 0$$

$\Rightarrow$  slow shock

$\Rightarrow v_n \ll$  magnetosonic velocity

$\Rightarrow$  Can use earlier master equation

$\Rightarrow$  instead look at jump conditions

\* Tangential force balance (Eq 7)

$$m n_i v_i V_{t2} = - \frac{B_n}{4\pi} B_{ti}$$

\* Tangential E

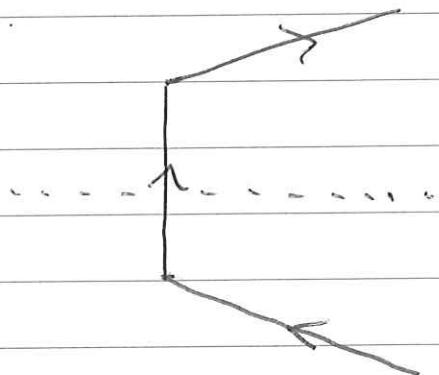
$$V_i B_{ti} = - V_{t2} B_n$$

$$\Rightarrow V_i B_{ti} = - B_n \left( - \frac{B_n}{4\pi} \frac{B_{ti}}{m n_i v_i} \right)$$

$$V_i^2 = \frac{B_n^2}{4\pi m n_i} \quad \Rightarrow \quad M_n^2 = \frac{V_i^2}{B_n^2} \frac{4\pi m n_i}{B_n^2} = 1$$

$$V_{t2} = - \frac{B_{t1}}{4\pi m n_1} \Rightarrow V_{t2} = C_{At1}$$

$\Rightarrow$  Alfvénic outflow



kink in  $B$  propagates up

$$C_{An} = \frac{B_n}{4\pi m n_1}$$

Inflow down flows at  $V_1$

$\Rightarrow V_1 = C_{An} \Rightarrow$  stationary

$\Rightarrow$  standing slow shock

Across the shock magnetic energy is dissipated.

$$B_{t1} \rightarrow B_{t2} = 0$$

\* pressure balance  $\Rightarrow$  inertia small,  
 $\Rightarrow$  sub magnetosonic flow

$$P_2 = \frac{B_{t1}^2}{8\pi}$$

\* energy flux

$$n_1 V_1 \frac{1}{2} m V_{t2}^2 + \frac{\Gamma}{\Gamma-1} P_2 \frac{V_1}{n} = \frac{B_{t1}^2}{4\pi} V_1$$

$$\text{with } n = \frac{n_2}{n_1}$$

$$\frac{V_1}{2} \left( \frac{B_{t1}^2}{4\pi} + \frac{\Gamma}{\Gamma-1} \frac{B_{t1}^2}{8\pi} \frac{V_1}{r} \right) = \frac{B_{t1}^2}{4\pi} V_1$$

$$V_1 \left( \frac{B_{t1}^2}{8\pi} + \frac{\Gamma}{\Gamma-1} \frac{B_{t1}^2}{8\pi} \frac{V_1}{r} \right) = \frac{B_{t1}^2}{4\pi} V_1$$

Kinetic  
disson

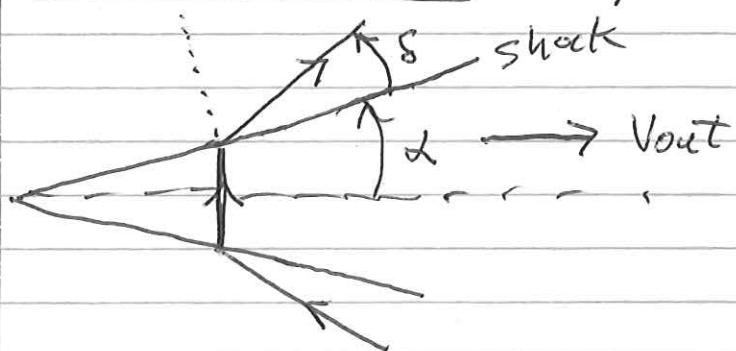
thermal  
disson

$\sim$   
mag up

$$r = \frac{\Gamma}{\Gamma-1} = \frac{5/3}{2/3} = \frac{5}{2}$$

$$r = \text{compression ratio} = \frac{5}{2}$$

Shock angles  $\alpha, \delta$



Downstream flow is horizontal

$\Rightarrow$  vertical flow is zero

$$V_{t2} \sin \alpha - V_{n2} \cancel{\cos \alpha} = 0$$

$$\alpha \ll 1$$

$$V_{t2} \alpha = V_{n2} = \frac{n_1 V_1}{n_2} = \frac{V_1}{r}$$

$$\boxed{\alpha = \frac{V_1}{CA_1} \frac{1}{r}}$$

$$\delta \sim \frac{B_n}{B_{t1}} = \frac{V_1}{CA_1}$$

$$\boxed{\delta \sim \frac{V_1}{CA_1}} \quad \Rightarrow \delta \sim \alpha r > \alpha$$